



COLLEGE OF ENGINEERING & TECHNOLOGY

Department: Mechanical Engineering

Lecturer : Prof. Dr. Kamal Abdelaziz Ibrahim & Prof.Dr. Ashraf S. Ismail

Course Title: Fluid Mechanics

Course Code: ME461

Date: 12/1/2015

Marks: 40

Time: 2:00-4:00

Final Exam

FINAL EXAMINATION PAPER

Answer all the Following Questions:

1-a: Starting with Navier-stokes equations, derive an equation for estimating the volume flow rate through a circular pipe of radius (R) . Assuming the flow is viscous incompressible and steady.

(4Marks)

1-b: Differentiate clearly between the following items:

- a- Uniform and Non-uniform flow.
- b- Free vortex and Forced vortex flow.
- c- Steady and unsteady flow.
- d- Laminar and turbulent flow.

(4Marks)

2- Find an expression for the acceleration vector of a fluid particle

as it moves through the point (1,1) in steady two dimensional flow described by ; $|V| = 2xy\sqrt{(x^2 + y^2)}$ with $xy = c$ (Streamline Equation) , where; C is constant.

Find also the velocity potential if it exists. (8Marks)

3- The velocity component (v) in the y direction for a certain steady incompressible two- dimensional ideal flow field is given by

$$v = x^2 - y^2$$

- a- Describe this flow field.
- b- Determine the value of pressure gradient in the x- direction ($\partial p / \partial x$) at a point (1, 2). Neglect body forces .
- C- locate any stagnation point in the flow field.

(8Marks)

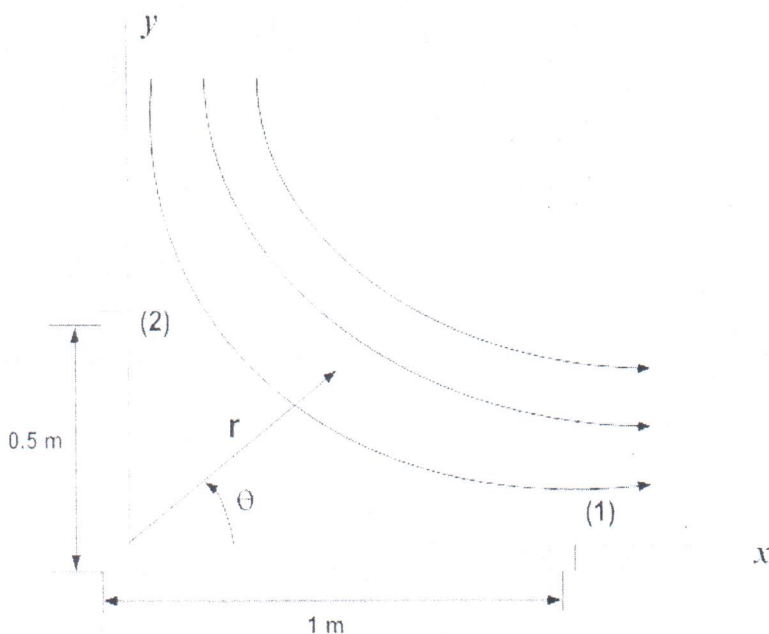
Members of Course Examination Committee:	Signature:	Date:
Lecturer: Prof.Dr Kamal Abdelaziz Prof.Dr. Ashraf Ismail		
Course Coordinator: Prof. Kamal Abdelaziz		
Head of Department: Prof. Dr. Elsaied Saber		

- 4- The two-dimensional flow of an inviscid, incompressible fluid flow in the vicinity of the 90° corner, as shown in the figure, is described by the stream function, ($\Psi = 2r^2 \sin 2\theta$) where Ψ has units of m^2/s , and r is in m.

Assume the fluid density is 1000 kg/m^3 and the x-y plane is horizontal (that is, there is no difference in elevation between points 1 and 2).

- Determine, if possible the corresponding velocity potential.
- What is the pressure at point (2) if the pressure at point (1) is 30 kPa ?

(8 Marks)



5-A two dimensional flow field is formed by adding a c.w free vortex at the origin of the coordinate system to the velocity potential $\phi = r^2 \cos 2\theta$. Find

- The pressure variation along (r)
- Locate any stagnation points in the flow field for plane ($0 \leq \theta \leq \pi$)

(8Marks)

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List of formulae:

$$\vec{V} = u \vec{i} + v \vec{j} + w \vec{k} \quad , \quad \frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w} \quad (\text{Equations for streamlines})$$

$$\frac{dy}{dx} = \tan \theta = \frac{v}{u} \quad (\text{For two-dimensional flow})$$

$$\vec{a} = a_x \vec{i} + a_y \vec{j} + a_z \vec{k}$$

$$a_x = \frac{Du}{Dt} = \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \quad , \quad a_y = \frac{Dv}{Dt} = \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}$$

$$a_z = \frac{Dw}{Dt} = \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

$$\vec{\nabla} \cdot \vec{V} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \quad , \quad \gamma = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \quad (\text{For two-dimensional flow})$$

$$\vec{\nabla} \times \vec{V} = \vec{\zeta} = 2 \vec{\omega} = \zeta_x \vec{i} + \zeta_y \vec{j} + \zeta_z \vec{k} = 2 (\omega_x \vec{i} + \omega_y \vec{j} + \omega_z \vec{k})$$

$$\omega_x = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \quad , \quad \omega_y = \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \quad , \quad \omega_z = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

$$\text{If } \vec{\nabla} \times \vec{V} = 0 \quad , \quad \vec{V} = \vec{\nabla} \phi \quad , \quad \vec{V} = \frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k}$$

$$u = \frac{\partial \phi}{\partial x} \quad , \quad v = \frac{\partial \phi}{\partial y} \quad , \quad w = \frac{\partial \phi}{\partial z} \quad , \quad v_r = \frac{\partial \phi}{\partial r} \quad , \quad v_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta} \quad , \quad v_z = \frac{\partial \phi}{\partial z}$$

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{V}) = 0 \quad , \quad \frac{\partial \rho}{\partial t} + \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial(\rho r v_r)}{\partial r} + \frac{1}{r} \frac{\partial(\rho r v_\theta)}{\partial \theta} + \frac{\partial(\rho v_z)}{\partial z} = 0 \quad , \quad \vec{\nabla} \cdot \vec{V} = 0 \quad (\text{Incompressible flow})$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad , \quad \frac{1}{r} \frac{\partial(r v_r)}{\partial r} + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} = 0 \quad \xi_z = \frac{1}{r} \left(\frac{\partial(r v_\theta)}{\partial r} - \frac{\partial v_r}{\partial \theta} \right)$$

$$u = \frac{\partial \psi}{\partial y} \quad , \quad v = -\frac{\partial \psi}{\partial x} \quad , \quad v_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta} \quad , \quad v_\theta = -\frac{\partial \psi}{\partial r}$$

$$\rho \vec{g} - \vec{\nabla} p = \rho \left(\frac{\partial \vec{V}}{\partial t} + (\vec{V} \cdot \vec{\nabla}) \vec{V} \right) \quad , \quad \rho g_x - \frac{\partial p}{\partial x} = \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right)$$

$$\rho g_y - \frac{\partial p}{\partial y} = \rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) \quad , \quad \rho g_z - \frac{\partial p}{\partial z} = \rho \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right)$$

$$\rho g_r - \frac{\partial p}{\partial r} = \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + v_z \frac{\partial v_r}{\partial z} - \frac{v_\theta^2}{r} \right)$$

$$\rho g_\theta - \frac{1}{r} \frac{\partial p}{\partial \theta} = \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + v_z \frac{\partial v_\theta}{\partial z} + \frac{v_r v_\theta}{r} \right)$$

$$\rho g_z - \frac{\partial p}{\partial z} = \rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right)$$

$$\frac{p}{\rho} + \frac{V^2}{2} + gZ = \text{constant} \quad , \quad V^2 = u^2 + v^2 \quad , \quad V^2 = v_r^2 + v_\theta^2$$

$$\text{Uniform flow: } \psi = U(y \cos \alpha - x \sin \alpha) \quad , \quad \phi = U(x \cos \alpha + y \sin \alpha)$$

$$\text{Source: } \psi = \frac{m}{2\pi} \theta \quad , \quad \phi = \frac{m}{2\pi} \ln r$$

$$\text{Sink: } \psi = -\frac{m}{2\pi} \theta \quad , \quad \phi = -\frac{m}{2\pi} \ln r$$

$$\text{Vortex: } \psi = -\frac{\Gamma}{2\pi} \ln r \quad , \quad \phi = \frac{\Gamma}{2\pi} \theta$$

$$\text{Doublet: } \psi = -\frac{k}{r} \sin \theta \quad , \quad \phi = \frac{k}{r} \cos \theta$$

Navier-Stokes Equations

(x direction)

$$\rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = -\frac{\partial p}{\partial x} + \rho g_x + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

(y direction)

$$\rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) = -\frac{\partial p}{\partial y} + \rho g_y + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right)$$

(z direction)

$$\rho \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) = -\frac{\partial p}{\partial z} + \rho g_z + \mu \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)$$

(r direction)

$$\begin{aligned} \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) \\ = -\frac{\partial p}{\partial r} + \rho g_r + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_r}{\partial r} \right) - \frac{v_r}{r^2} + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right] \end{aligned}$$

(θ direction)

$$\begin{aligned} \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) \\ = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_\theta + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_\theta}{\partial r} \right) - \frac{v_\theta}{r^2} + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right] \end{aligned}$$

(z direction)

$$\begin{aligned} \rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) \\ = -\frac{\partial p}{\partial z} + \rho g_z + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] \end{aligned}$$